

Improving rainfall gradients modeling by conditioning daily rainfall maps to monthly totals



Lionel Benoit, Denis Allard

Matthew Lucas, Keri Kodama, Thomas Giambelluca

April 2025 - Workshop



GEOLEARNING
CHAIRE /// Data Science for the Environment

with support from



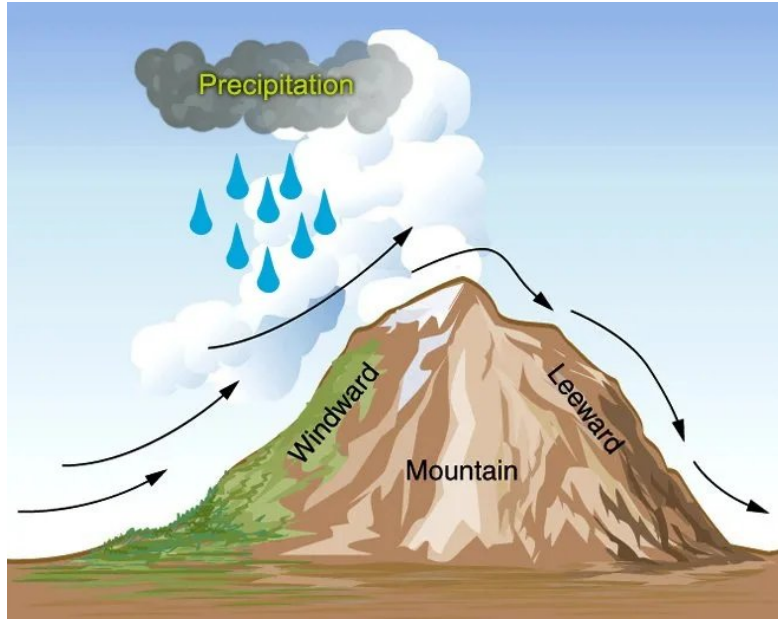
INRAE 390/Π



UNIVERSITY of HAWAI'I at MĀNOA
WATER RESOURCES RESEARCH CENTER

Introduction (1/5): orographic rainfall leads to strong spatial gradients

Orographic rainfall:

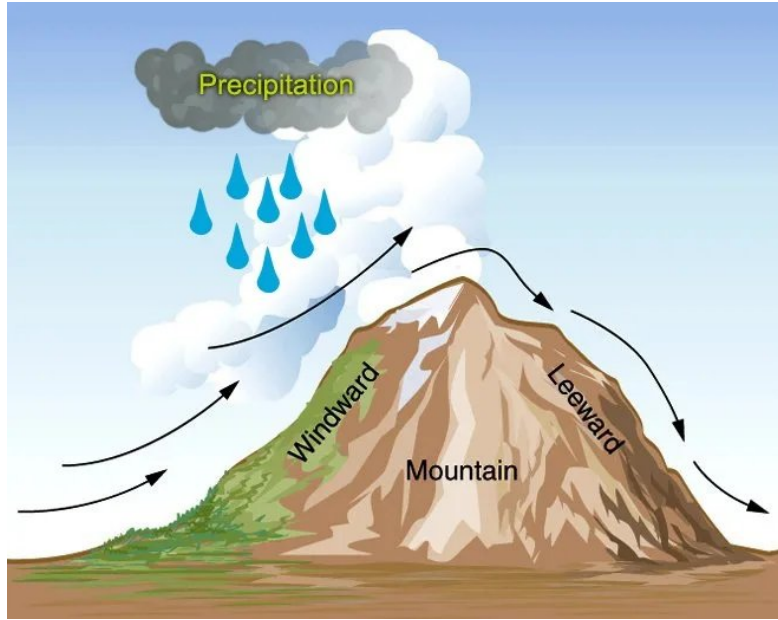


Orographic precipitation is ubiquitous:

- *Mediterranean climate: Sierra Nevada (Spain & USA)*
- *Temperate climate: Alpes*
- *Tropical climate: Andes & High tropical islands*

Introduction (1/5): orographic rainfall leads to strong spatial gradients

Orographic rainfall:

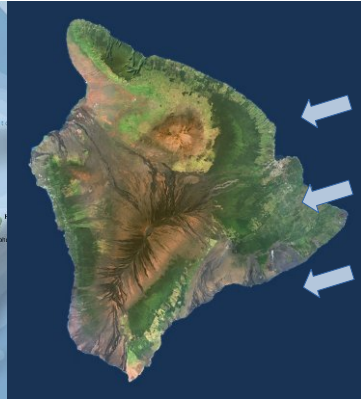
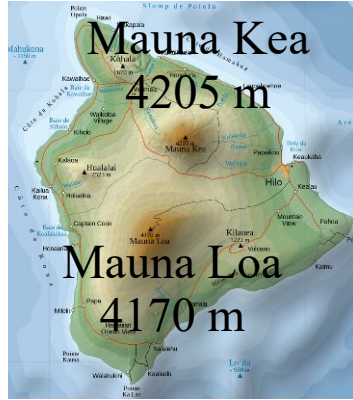


And impacts rainfall statistics:

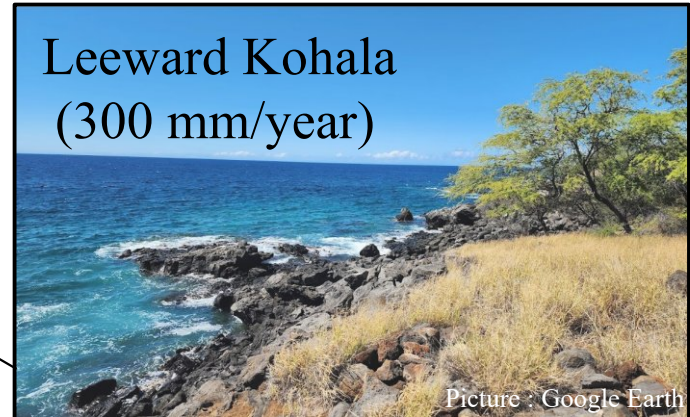
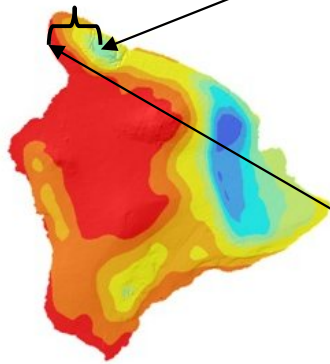
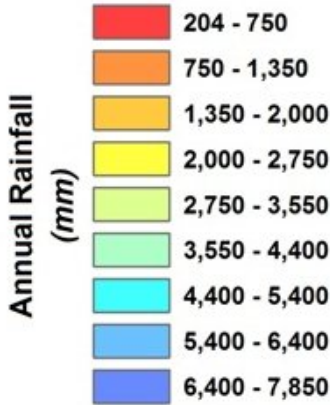
- *Rainfall statistics vary in space (occurrence, intensity, dependencies)*
- *Not simply related to covariates (e.g., elevation, slope, weather)*

Introduction (2/5): the example of Hawai‘i Island

Hawai‘i is a textbook study area for orographic rainfall:



Distance = 20 km

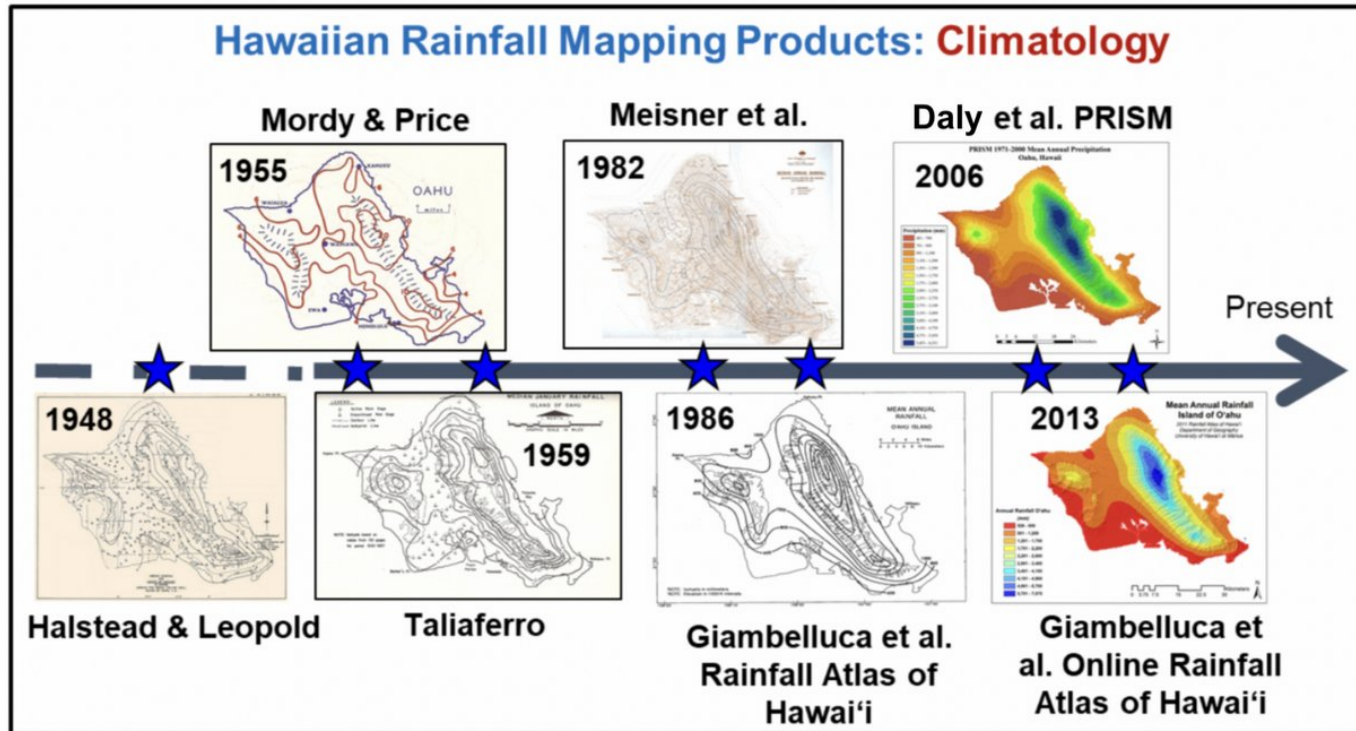


Introduction (3/5): rainfall mapping in Hawai‘i

Climatological rainfall maps:

→ *Long time series of rainfall observations (rain gauges only)*

→ *Vegetation proxies to complement direct observations in poorly gauged areas*



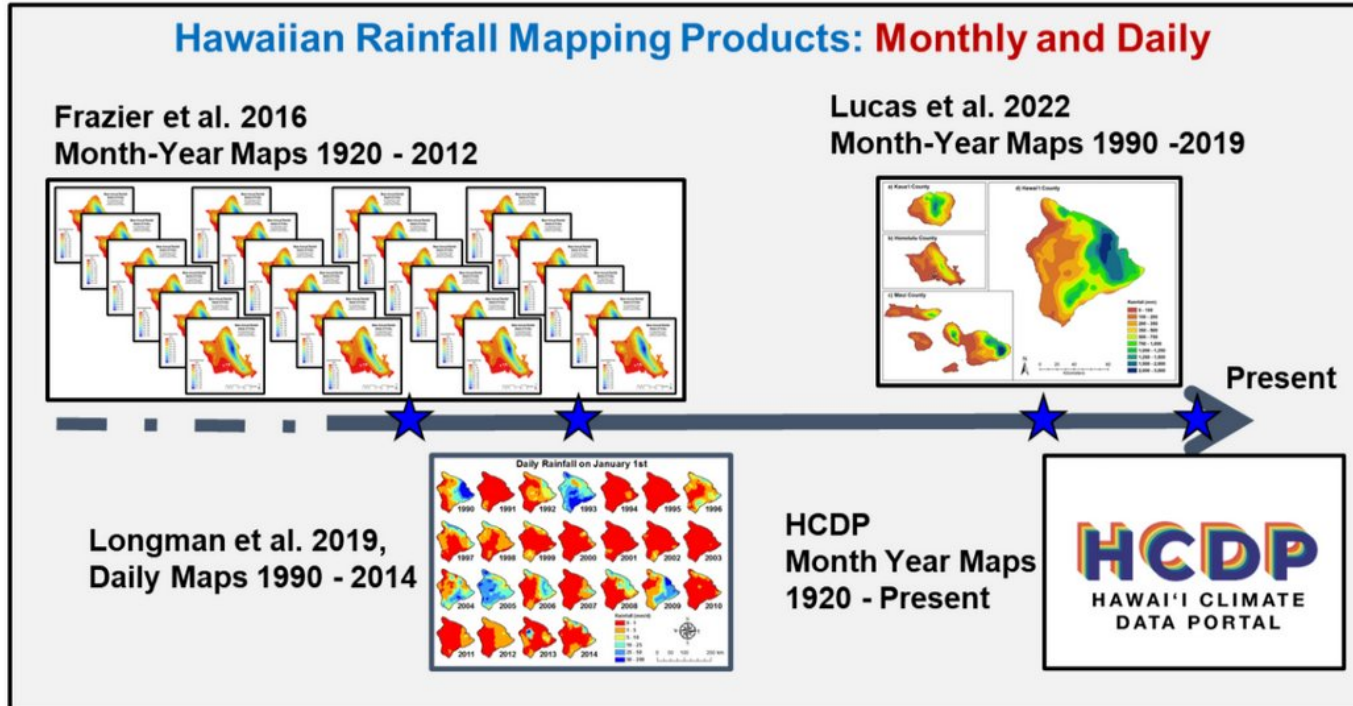
Picture : www.hawaii.edu/climate-data-portal

Introduction (4/5): rainfall mapping in Hawai‘i

Monthly and daily rainfall maps:

→ *Input data = rain gauge observations + climatological maps*

→ *Climatologically aided interpolation (i.e., KED with drift from the climatology)*



Picture : www.hawaii.edu/climate-data-portal

Introduction (5/5): objectives of this work

Improve uncertainty quantification

→ *Replace Kriging by conditional simulations*

Account for non-stationary rain statistics

→ *Spatial model accounting for non-stationary marginals and dependencies*

→ *Parameter inference from rain gauge observations (spatially sparse)*

Condition daily rainfall maps to monthly totals

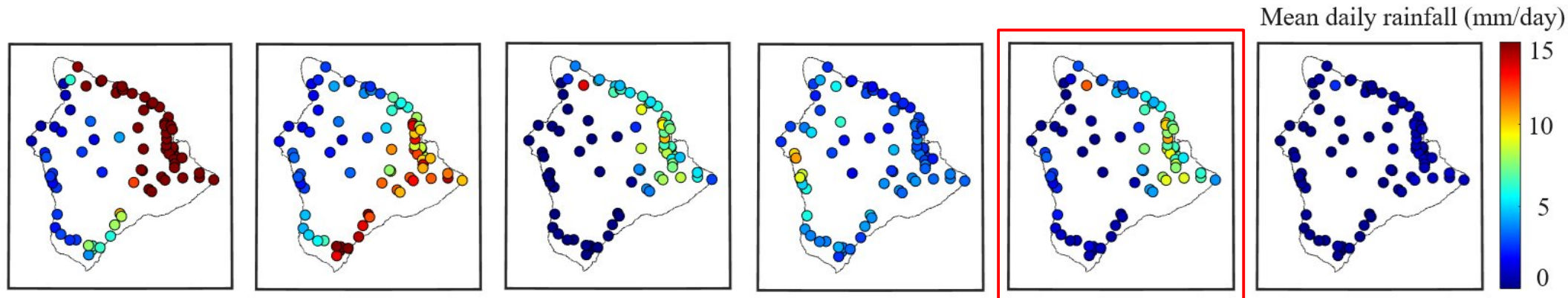
→ *Better capture the spatial gradients in poorly gauged areas*

→ *Ensure consistency between monthly and daily maps*

Rainfall model (1/5): rain types

Orographic effects depend on atmospheric conditions:

- Days with similar rainfall are pooled into **rain types** and **processed separately**.
- One [purely spatial] stochastic model is set-up for each rain type.



Trade wind conditions (used for illustration)

=> shallow convection & distinctive orographic effects

=> around 50% of the dataset

Rainfall model (2/5): trans-Gaussian Random Field

Trans-Gaussian geostatistics split the rain signal (R) in two components:

$$Y \sim \text{MVN}(0, 1, C_Y) \quad \text{and}$$

$$R = \psi(Y)$$

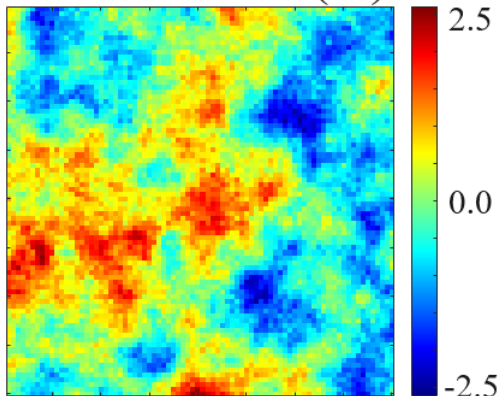
Latent field:

Models spatial dependencies through the covariance function C_Y

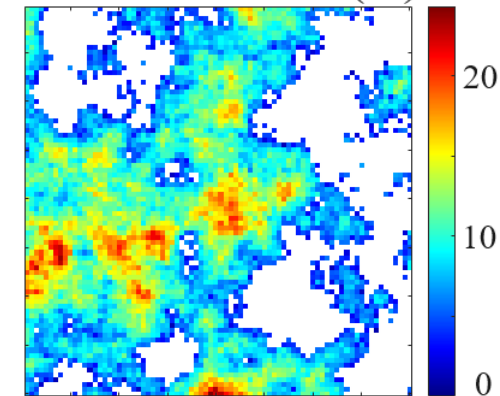
Transform function:

Models rainfall occurrence and intensity

Latent field (Y)



Rainfall field (R)



Rainfall model (2/5): trans-Gaussian Random Field

Trans-Gaussian geostatistics split the rain signal (R) in two components:

$$Y \sim \text{MVN}(0, 1, C_Y) \quad \text{and}$$

$$R = \psi(Y)$$

Latent field:

Models spatial dependencies through the covariance function C_Y

Transform function:

Models rainfall occurrence and intensity

C_Y parameterized by a Matérn covariance function

ψ parameterized by the mixture of an atom of zeros (truncation) and a Gamma distribution

$$C_Y(\|\mathbf{h}\|; \nu, \rho) = \frac{1}{\Gamma(\nu)2^{\nu-1}} \left(\frac{\|\mathbf{h}\|}{\rho} \right)^\nu \mathcal{K}_\nu \left(\frac{\|\mathbf{h}\|}{\rho} \right)$$

$$\begin{aligned} R(\mathbf{s}) &= 0 & \text{if } Y(\mathbf{s}) \leq a_0 \\ R(\mathbf{s}) &= \text{Gamma}^{-1}(\Phi(Y(\mathbf{s})); k, \theta) & \text{if } Y(\mathbf{s}) > a_0 \end{aligned}$$

Rainfall model (3/5): making the model non-stationary

Non-stationary model to capture the spatial variation of rain statistics:

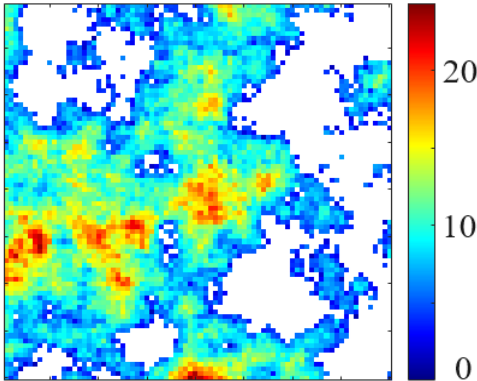
=> Model parameters are made location-dependent:

→ $\psi \Rightarrow \psi_s$ and $C_Y \Rightarrow C_{Ys}$ (with s the location of interest)

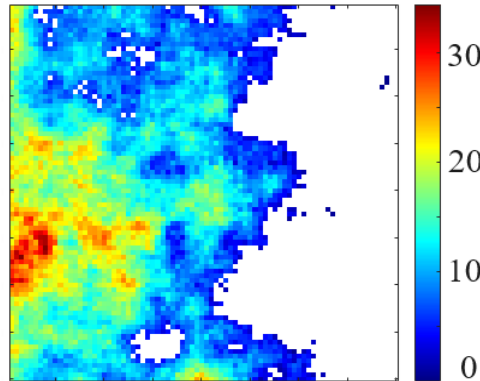
→ C_{Ys} requires a valid model of non-stationary covariance

[Paciorek & Schervish, 2006, spatial modelling using a new class of non-stationary covariance functions, *Environmetric*, 17:483-506]

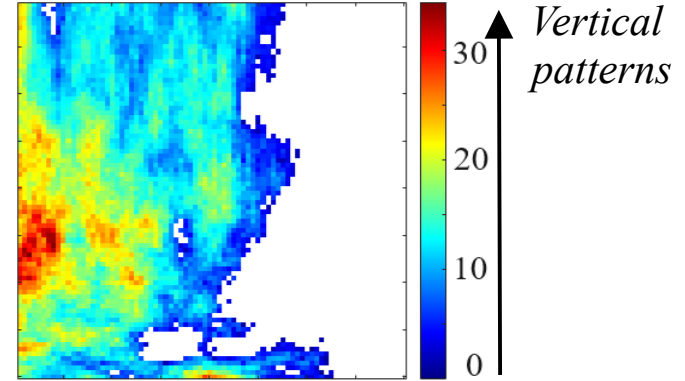
Stationary model



Non-stationary ψ



Non-stationary ψ and C_Y



High intensity → Low intensity

Rainfall model (3/5): making the model non-stationary

Non-stationary model to capture the spatial variation of rain statistics:

⇒ Model parameters are made location-dependent:

→ $\psi \Rightarrow \psi_{\mathbf{s}}$ and $C_Y \Rightarrow C_{Y_{\mathbf{s}}}$ (with \mathbf{s} the location of interest)

→ $C_{Y_{\mathbf{s}}}$ requires a valid model of non-stationary covariance

[Paciorek & Schervish, 2006, spatial modelling using a new class of non-stationary covariance functions, *Environmetric*, 17:483-506]

$$C_Y(\mathbf{s}_i, \mathbf{s}_j) = \frac{2^{1-(\nu_i+\nu_j)/2}}{\sqrt{\Gamma(\nu_i)\Gamma(\nu_j)}} |\boldsymbol{\Sigma}_i|^{\frac{1}{4}} |\boldsymbol{\Sigma}_j|^{\frac{1}{4}} \left| \frac{\boldsymbol{\Sigma}_i + \boldsymbol{\Sigma}_j}{2} \right|^{-\frac{1}{2}} \left(\sqrt{Q_{ij}} \right)^{\frac{\nu_i+\nu_j}{2}} \mathcal{K}_{\frac{\nu_i+\nu_j}{2}} \left(\sqrt{Q_{ij}} \right)$$

$$\text{with } \boldsymbol{\Sigma}_i = \mathbf{V}_i \times \boldsymbol{\Lambda}_i \times \mathbf{V}_i^T; \quad \mathbf{V}_i = \begin{bmatrix} \frac{\gamma_{1,i}}{\sqrt{\gamma_{1,i}^2 + \gamma_{2,i}^2}} & -\frac{\gamma_{2,i}}{\sqrt{\gamma_{1,i}^2 + \gamma_{2,i}^2}} \\ \frac{\gamma_{2,i}}{\sqrt{\gamma_{1,i}^2 + \gamma_{2,i}^2}} & \frac{\gamma_{1,i}}{\sqrt{\gamma_{1,i}^2 + \gamma_{2,i}^2}} \end{bmatrix}; \quad \boldsymbol{\Lambda}_i = \begin{bmatrix} \gamma_{1,i}^2 + \gamma_{2,i}^2 & 0 \\ 0 & \lambda_{2,i} \end{bmatrix}$$

$$\text{and with } Q_{ij} = (\mathbf{s}_i - \mathbf{s}_j)^T \left(\frac{\boldsymbol{\Sigma}_i + \boldsymbol{\Sigma}_j}{2} \right)^{-1} (\mathbf{s}_i - \mathbf{s}_j)$$

Rainfall model (4/5): parameter estimation

Model parameters are estimated by likelihood maximization

→ Overall 9 parameters

Estimation of model parameters from sparse observations

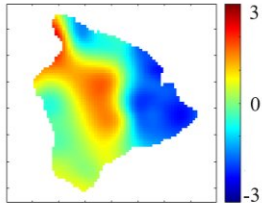
→ Marginal distribution (ψ_s): estimation at gauge locations + Ordinary Kriging

→ Covariance function (C_{Y_S}): estimation within climate division + Spline interp.

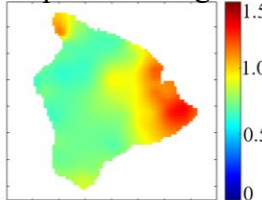
Example for RainType 5

Parameters of the marginal distr. Ψ

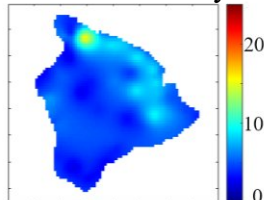
$a_0 \approx$ proba. dry day



$k \approx$ proba. strong rain



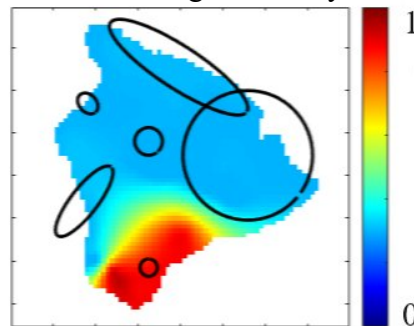
$\theta \approx$ rain intensity



Parameters of the covariance C_Y

Background :

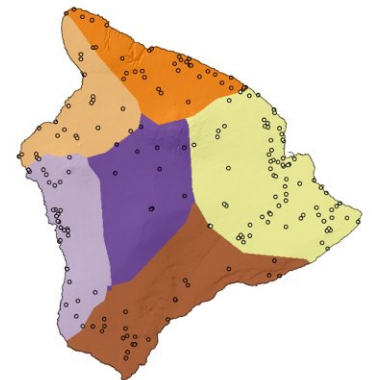
$v \approx$ short lag variability



On top:

Ellipses of anisotropy \approx correlation distance

Hawai'i climate divisions



Rainfall model (5/5): simulation (unconditional)

(1) Unconditional simulation of the latent field (Y)

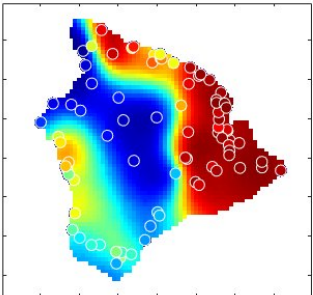
+ Transformation of the latent field into rain intensities: $R(\mathbf{s}) = \Psi(Y(\mathbf{s}))$

= Stochastic rainfall generation

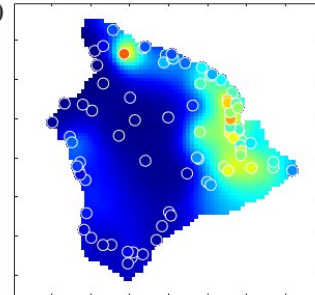
Example for RainType 5

Statistics of the marginal distribution

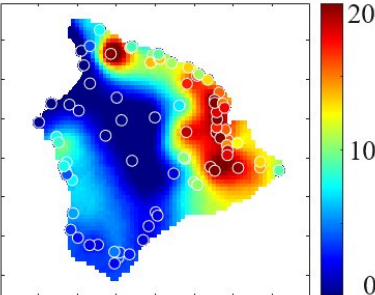
Rain occurrence (%)



Mean rainfall (mm/day)



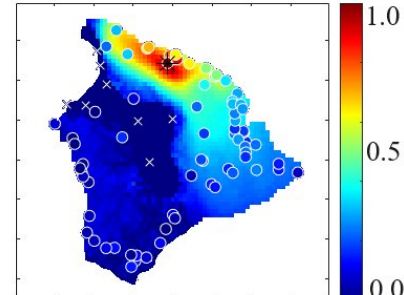
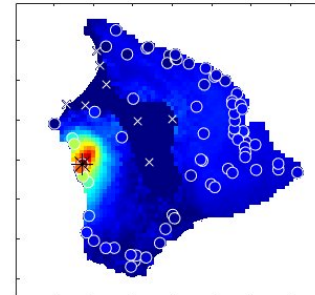
q_{90%} rainfall (mm/day)



dots = observations; background maps = simulations

Statistics of the spatial structure

Correlation with point *

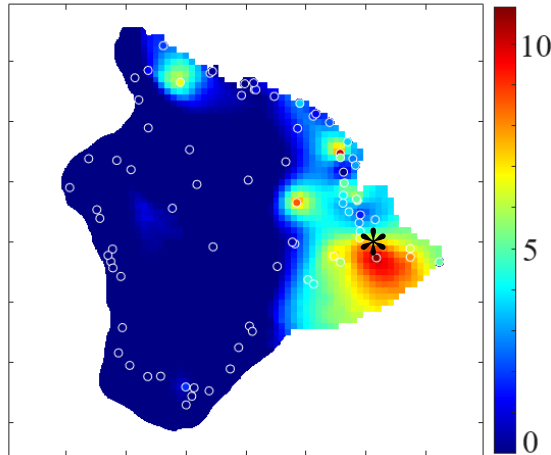


Rainfall model (5/5): simulation (conditional)

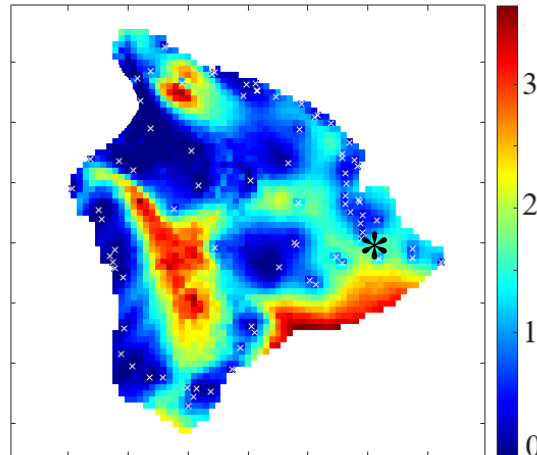
- (1) Unconditional simulation of the latent field (Y)
- (2) Simulation of censored latent values (dry obs.) by Gibbs sampler
- (3) Conditioning by conditional Kriging
- (4) Transformation of the latent field into rain intensities: $R(\mathbf{s}) = \Psi(Y(\mathbf{s}))$

Example for RainType 5

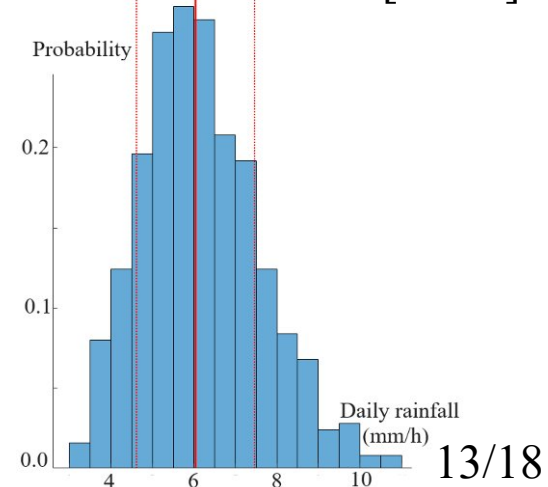
Estimated rainfall [$q_{50\%}$ sim.] (mm/day)



Uncertainty [1σ] (mm/day)



Probabilistic forecast [loc. *]



Conditioning to monthly totals (1/4): motivation

Uncertainties increase with the distance to rain gauges

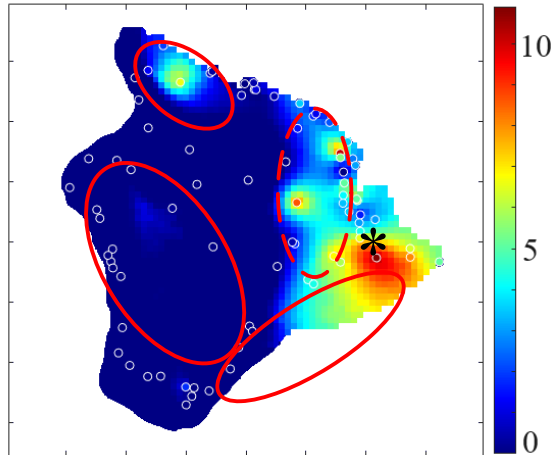
→ *Large uncertainties in poorly gauged areas and at the edges of the domain*

→ *Spatial gradients may be over-smoothed*

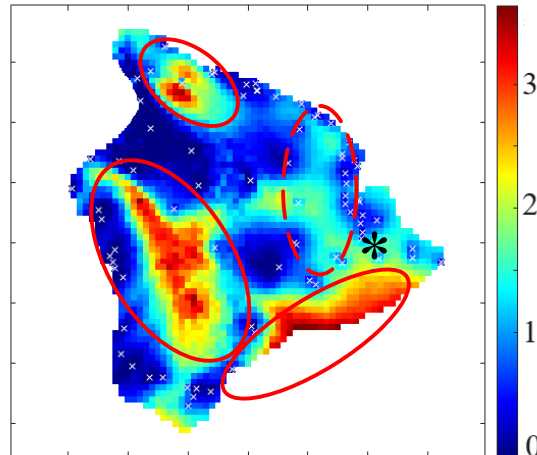
Use the spatial information from monthly maps to constrain the daily maps

Example for RainType 5

Estimated rainfall [q_{50%} sim.] (mm/day)



Uncertainty [1σ] (mm/day)



Conditioning to monthly totals (2/4): method

Challenge: different spatial models (i.e., rain types) during the same month

=> **Metropolis within Gibbs**

(1) *Select target locations and initialize their latent values*

(2) *For each location and each day:*

- Gibbs sampling conditional to (i) latent obs. and (ii) simu. at other target locations
- Transformation to get daily rainfall simulation at target location
- Acceptance following a Metropolis rule applied to monthly sum

(3) *Iterate (2) for warm-up period + sampling daily rainfall at target locations*

Other problem: low computational efficiency

=> **Metropolis within Gibbs to simulate a small set of ‘virtual stations’ (≈ 100)**

- + *Conditional simulation using (i) daily rain gauge observations*
- (ii) virtual stations pseudo-observations*

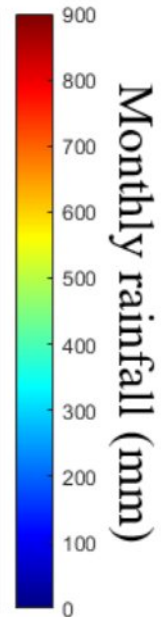
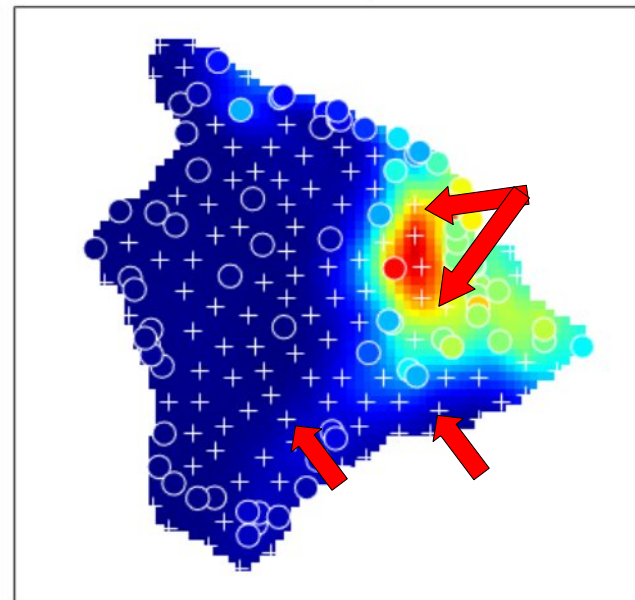
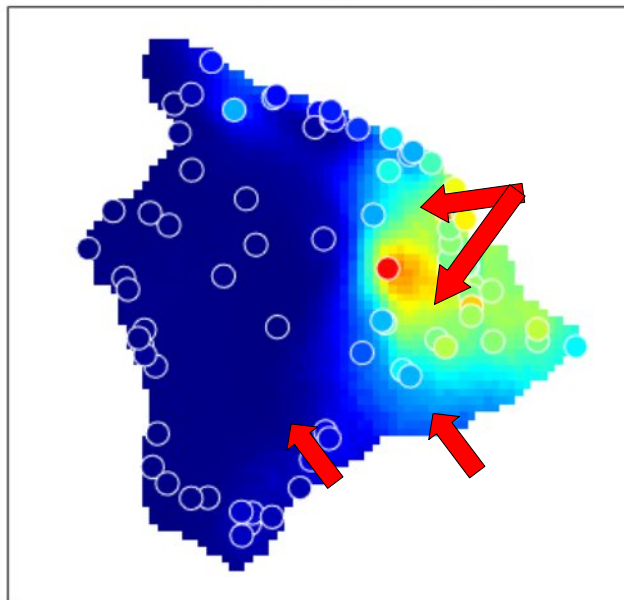
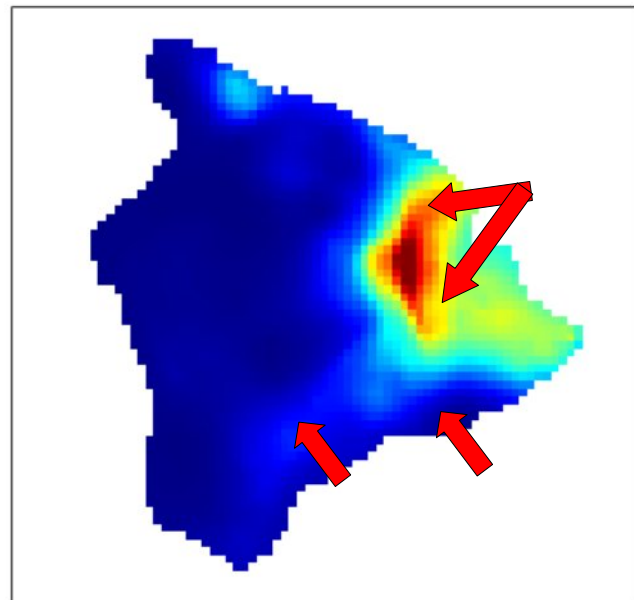
Conditioning to monthly totals (3/4): results - impact on monthly totals

January 2018

HCDP rain atlas

Stochastic interpolation
Rain gauges only

Stochastic interpolation
Rain gauges + virtual stations

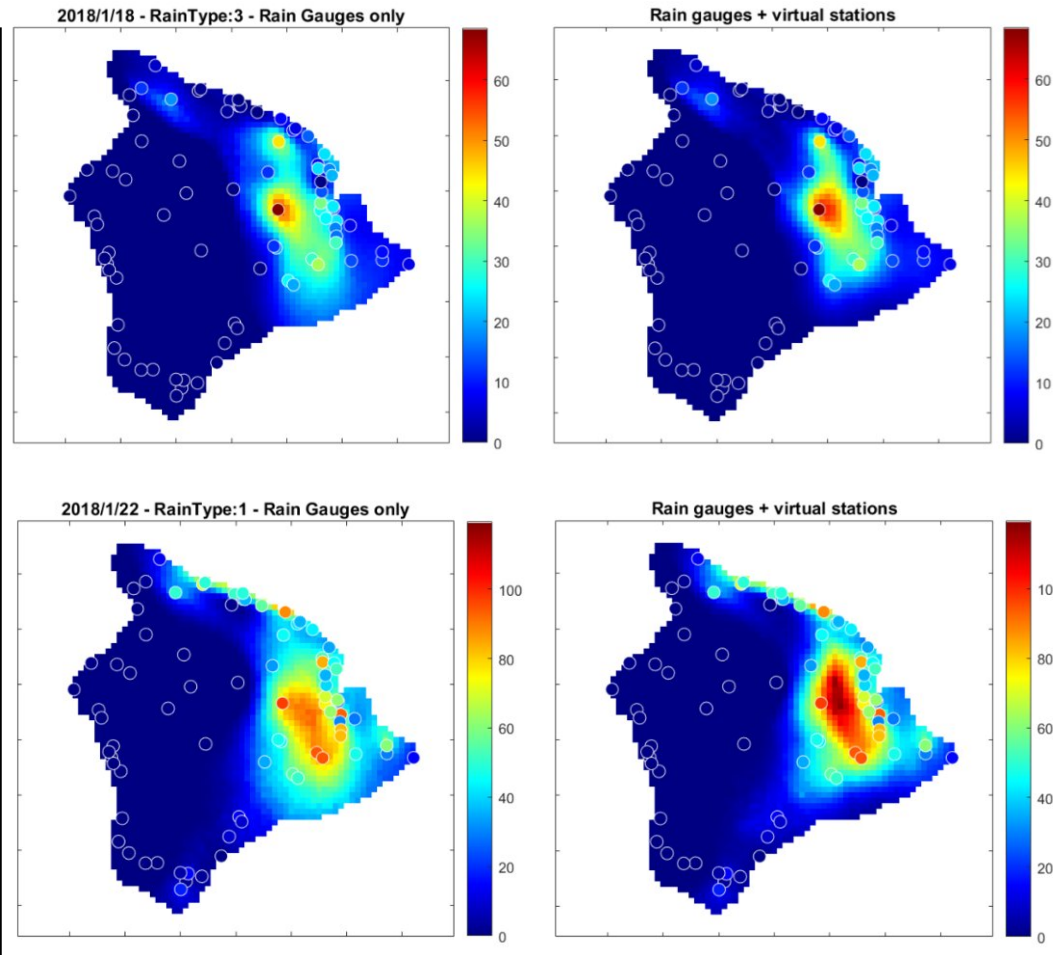


o Rain gauge
+ Virtual station

Conditioning to monthly totals (4/4): results - impact on daily maps

Improve gradients also in daily rainfall maps

Can simulate daily maximum between rain gauges



Conclusion & perspectives:

Non-stationary trans-Gaussian geostatistics:

- *Reproduce the statistical signature of daily rainfall in mountains*
- *Applications: (i) stochastic rainfall generator, (ii) rainfall mapping*

Conditioning to monthly totals:

- *Ensures consistency between rainfall maps at different time scales*
- *Improves the mapping of spatial gradients at the daily scale*

Next step: non-stationary space-time model for sub-daily orographic rainfall

- *Non-stationary space-time covariance functions (cf. presentation Denis)*
- *Diurnal cycle*

Thank you for your attention :-)

