

Deep Generative Models for Spatial and Spatiotemporal Simulation of Natural Phenomena

BHAVSAR Ferdinand

Equipe BIOSP
INRAE

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GEOLEARNING
CHAIRE // Data Science for the Environment

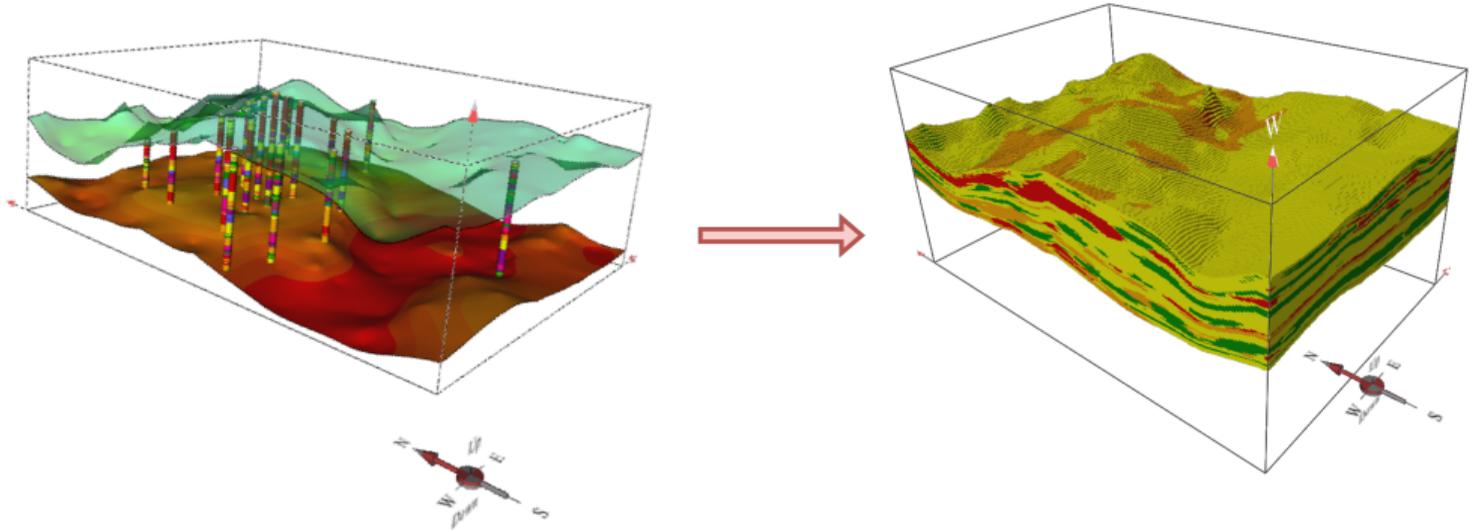


Collaboration with: [Thesis] DESASSIS Nicolas, ORS Fabien, ROMARY Thomas, [Postdoc] Edith Gabriel, Lionel Benoit

- ① Thesis research: Geological maps [Mines Paris]
- ② Postdoctoral research: Hydrographic time-series [INRAE]

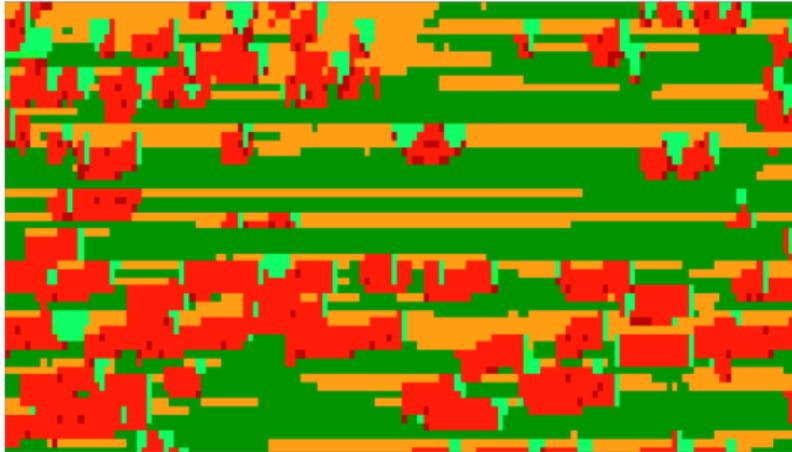
The problem: simulating sedimentary facies in an underground volume

Conditional simulation of sedimentary facies in an underground volume
How do we go from left to right? ("Fill the volume")

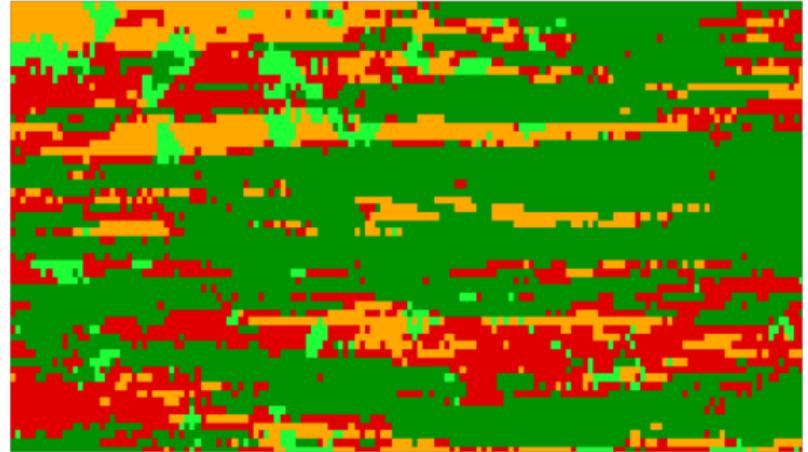


Source: *Isatis (Geostatistics)*, Mines Paris Study

Flexible, easily conditioned, but generally lack realism.



Reference simulation

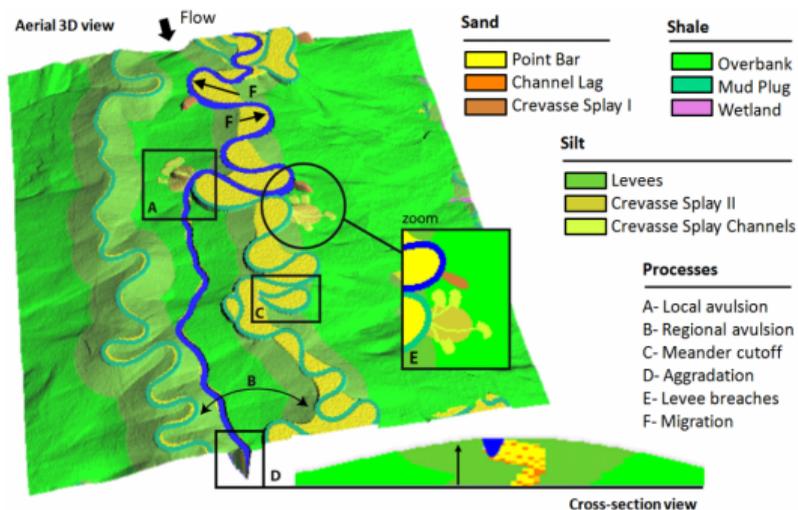


Plurigaussian simulation conditioned on wells
from left simulation

Source images: Weill 2013, Bubnova 2018

Process-based model: Flumy

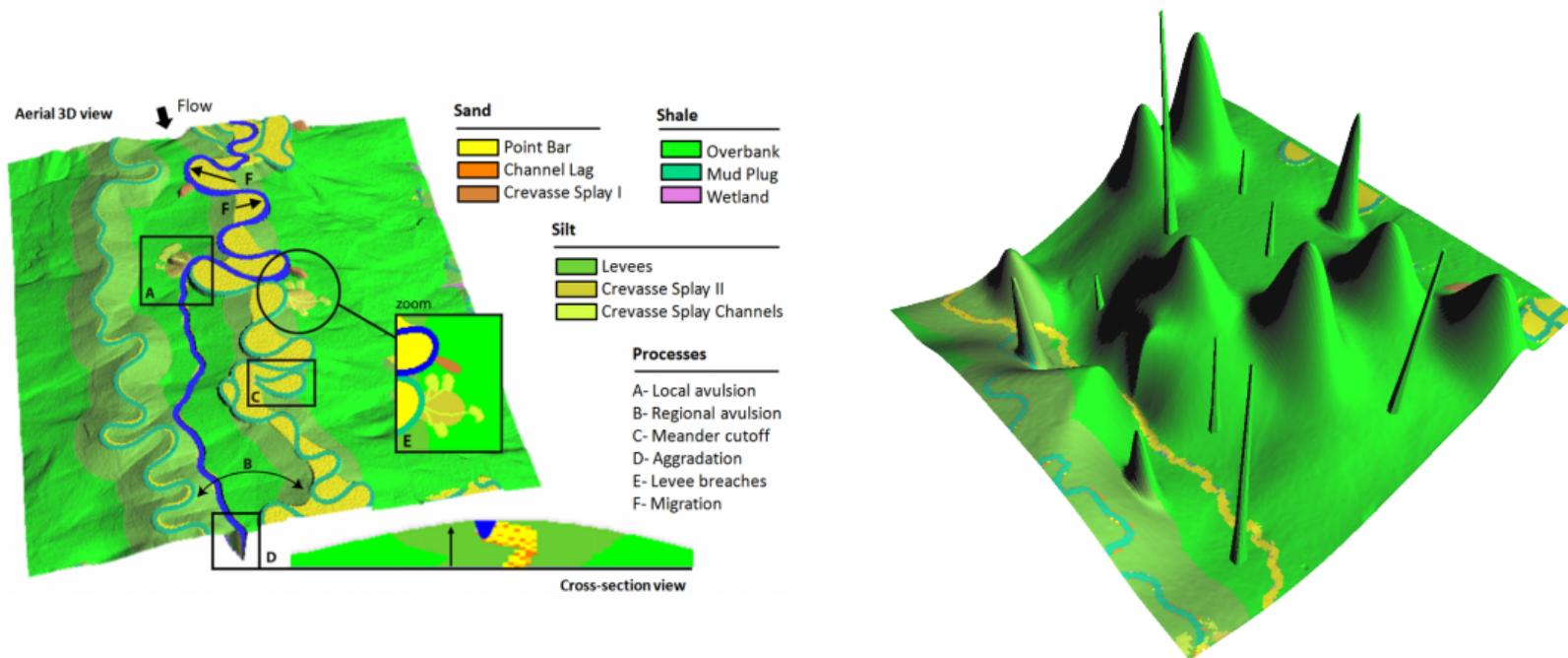
Flumy, a stochastic process-based model that produces **highly realistic simulations**, but is hard to condition (Lopez, 2003; Flumy-Userguide, 2022)



Source image: (Flumy-Userguide, 2022)

Process-based model: Flumy

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Problem

Given a dataset, we want to sample new, never-seen before, convincing simulations with the same properties as simulations from the dataset

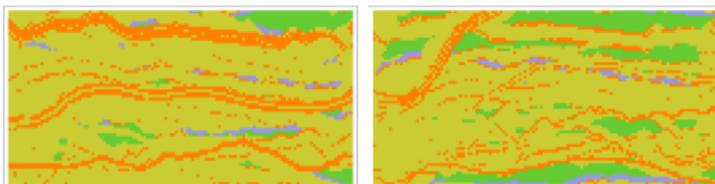
Problem

Given a dataset, we want to sample new, never-seen before, convincing simulations with the same properties as simulations from the dataset

Easy to sample Random Variable



Complex and unknown Random Variable (our images)



2D Training pictures, 5500 simulations with 4 possible facies, generated with Flumy

- ① Generative Adversarial Networks (GANs)
- ② Discrete denoising diffusion models (DDM)
- ③ Future research
- ④ Conclusion

① Generative Adversarial Networks (GANs)

GAN framework

Parametrized GAN

Conditioning GANs

② Discrete denoising diffusion models (DDM)

Categorical denoising diffusion

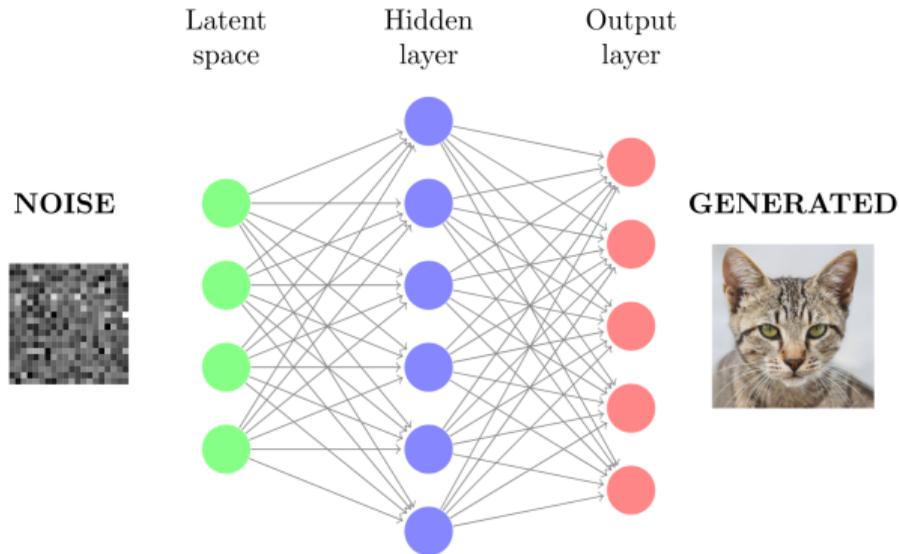
Conditioning DDMs

③ Future research

Modelizing hydrographic variables

④ Conclusion

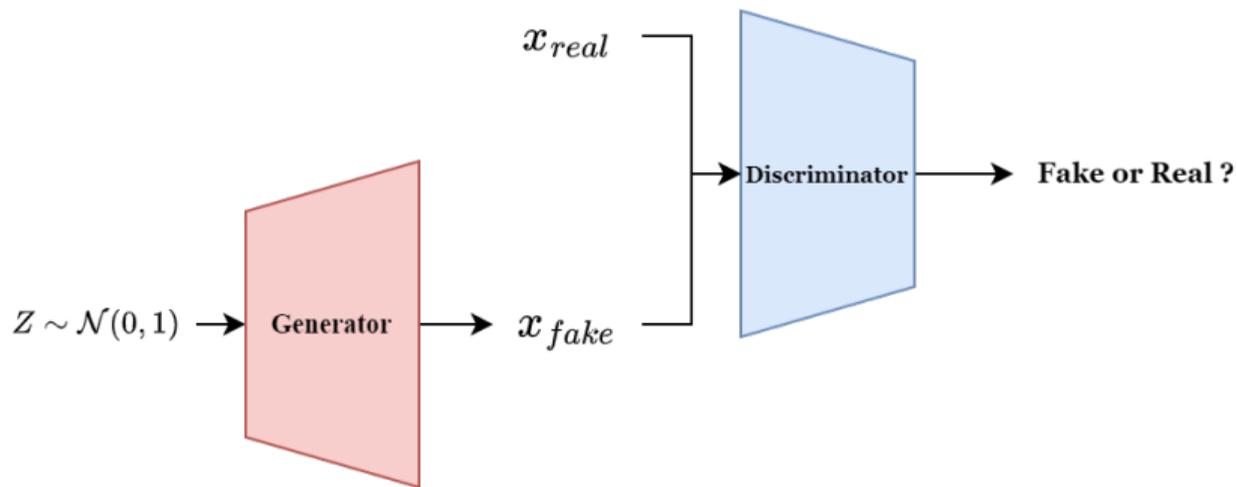
We want to find an approximation G_θ of a transformation G :



The generator defines a distribution p_θ . We want $p_\theta \approx p_r$.

The GAN framework

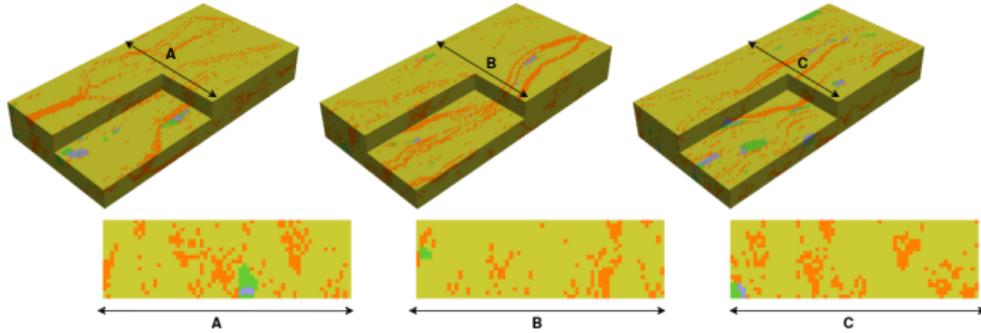
A generative framework inspired by game-theory:



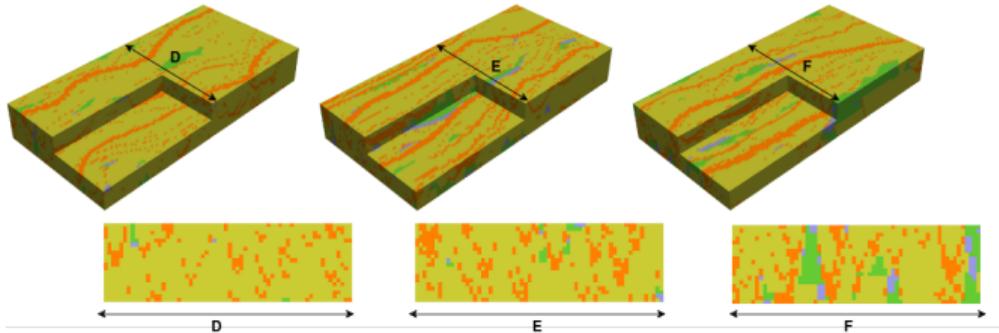
We optimise both models with gradient descent, each trying to maximize their own payoff The models compete on a min-max objective:

$$\arg \min_{\theta} \arg \max_{\phi} L(\theta, \phi)$$

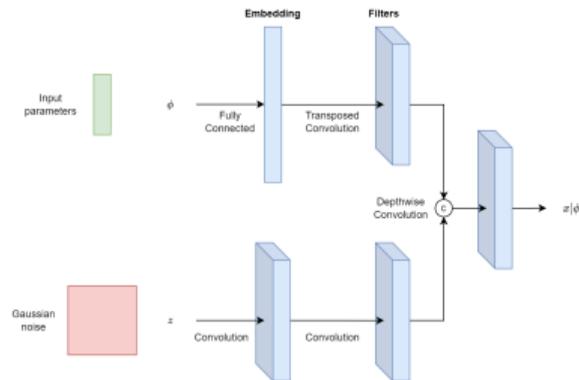
Generated Volumes + Cross-section



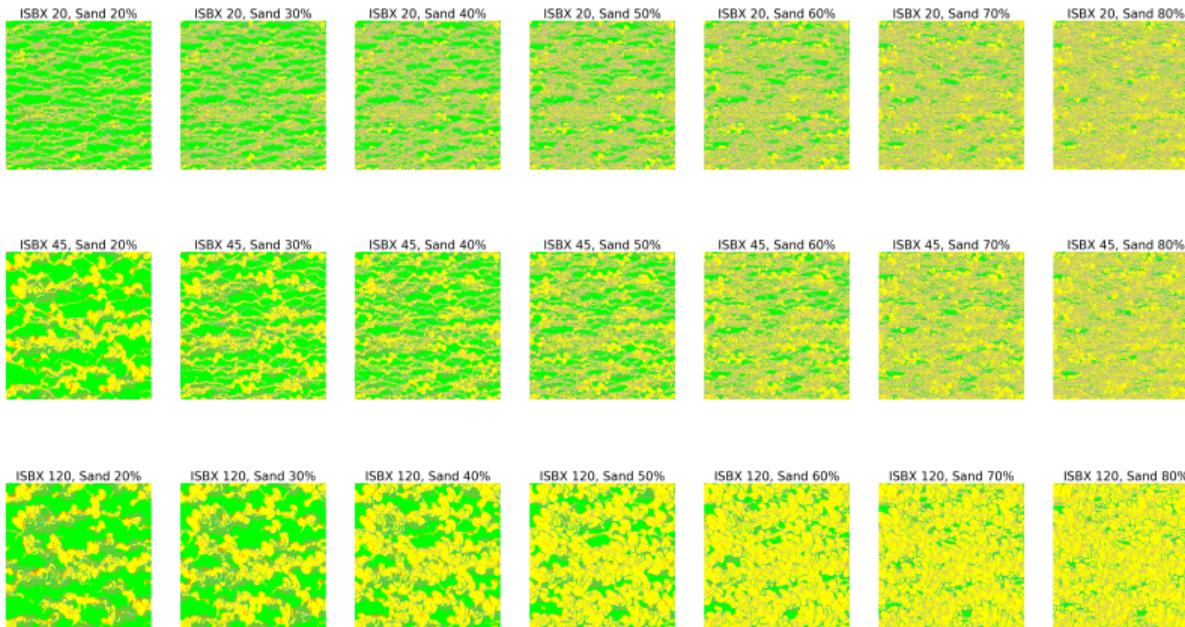
Flumy Volumes + Cross-section



Add a **second input** to the network.
[Conditional GAN (Mirza et al., 2014)]
Sand percentage and channel extension.

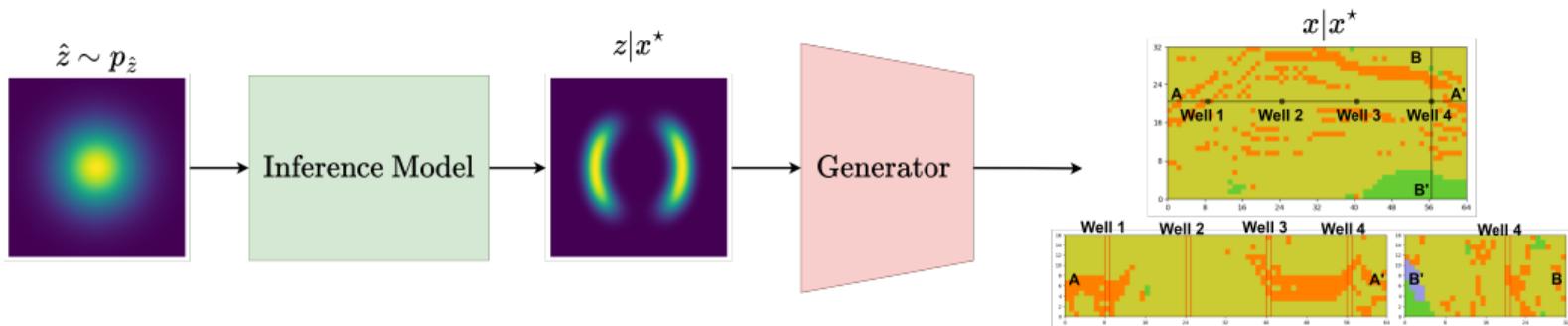


Parametrization: Result



Honouring the available data:

- Trained generator (prior model): $p(z)$
- Variational Bayes Conditioning: $p(z|x^*) \propto p(x^*|z)p(z)$
- Inference model learns this posterior distribution



We have l_ψ the inference model that transforms $\hat{z} \sim \mathcal{N}(0, I)$ into $z \sim q_\psi(z|x^*)$.
 Ψ are the parameters of the model.

Neural network

Neural Network l_ψ , Ψ the weights of the layers
(Chan and Elsheikh, 2019):

$$q_\psi(z|x^*) = l_\psi \# p(z)$$

Conditioning the GAN model

We have l_Ψ the inference model that transforms $\hat{z} \sim \mathcal{N}(0, I)$ into $z \sim q_\Psi(z|x^*)$.
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Gaussian mixture (Bhavsar et al., 2024)

We design an alternative $l_\Psi \rightarrow$ Gaussian Mixture. Ψ are the parameters of the Gaussian components:

$$q_\Psi(z|x^*) = \sum_{i=1}^K \pi_i f_{\mu_i, \Sigma_i}(z)$$

where $f_{\mu, \Sigma}$ is the Gaussian density with mean μ and covariance Σ .

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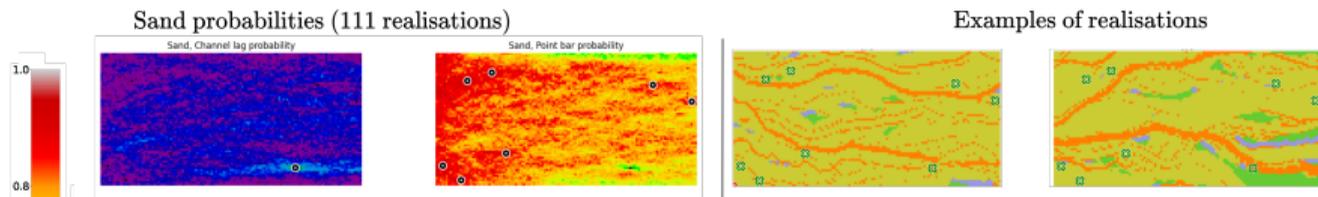
where $f_{\mu, \Sigma}$ is the Gaussian density with mean μ and covariance Σ .

$$\Psi^* = \underset{\Psi}{\operatorname{argmin}} D_{KL}(q_\psi(z|x^*) || p(z|x^*))$$

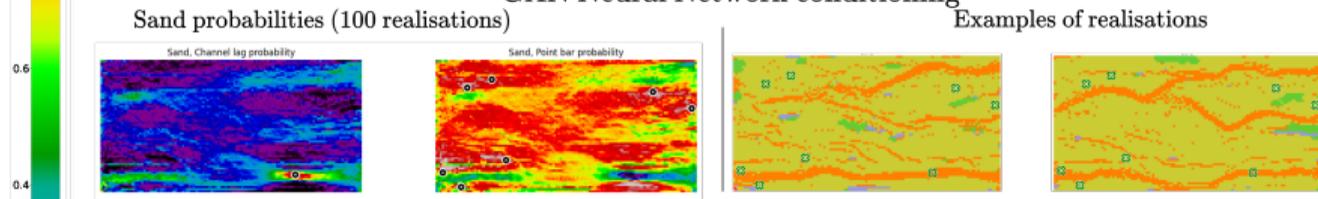
Conditioning the GAN model: results

Once the inference model is trained, thousands of realizations can be simulated at low cost. This allows us to compute metrics and statistics over conditioned simulations.

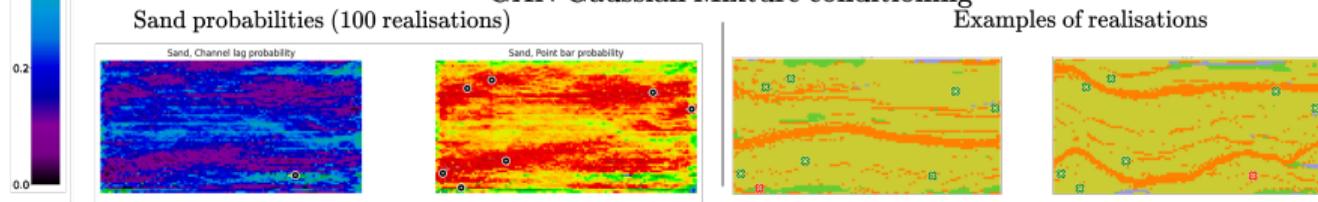
Generator simulations accept-reject



GAN Neural Network conditioning

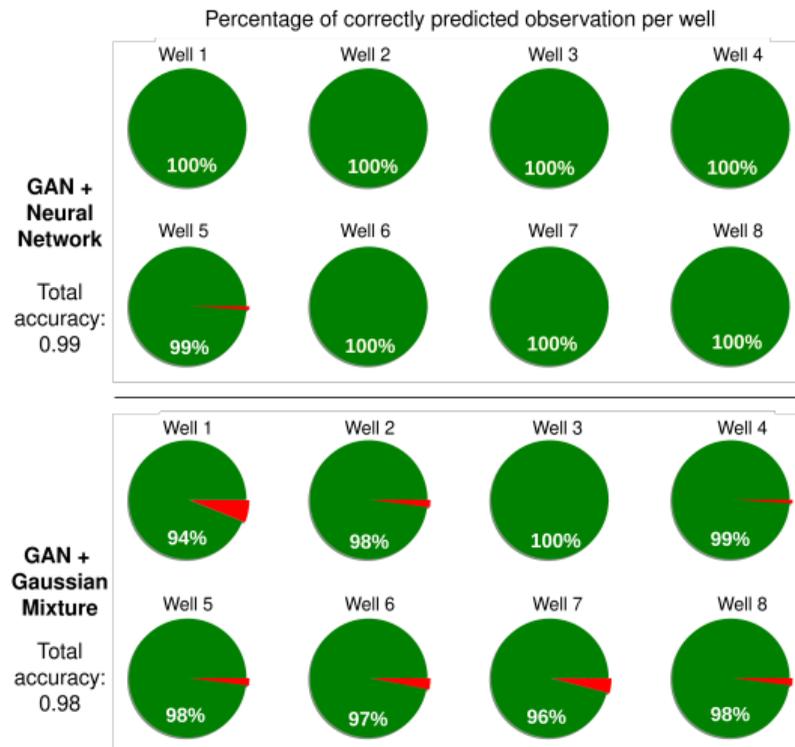


GAN Gaussian Mixture conditioning

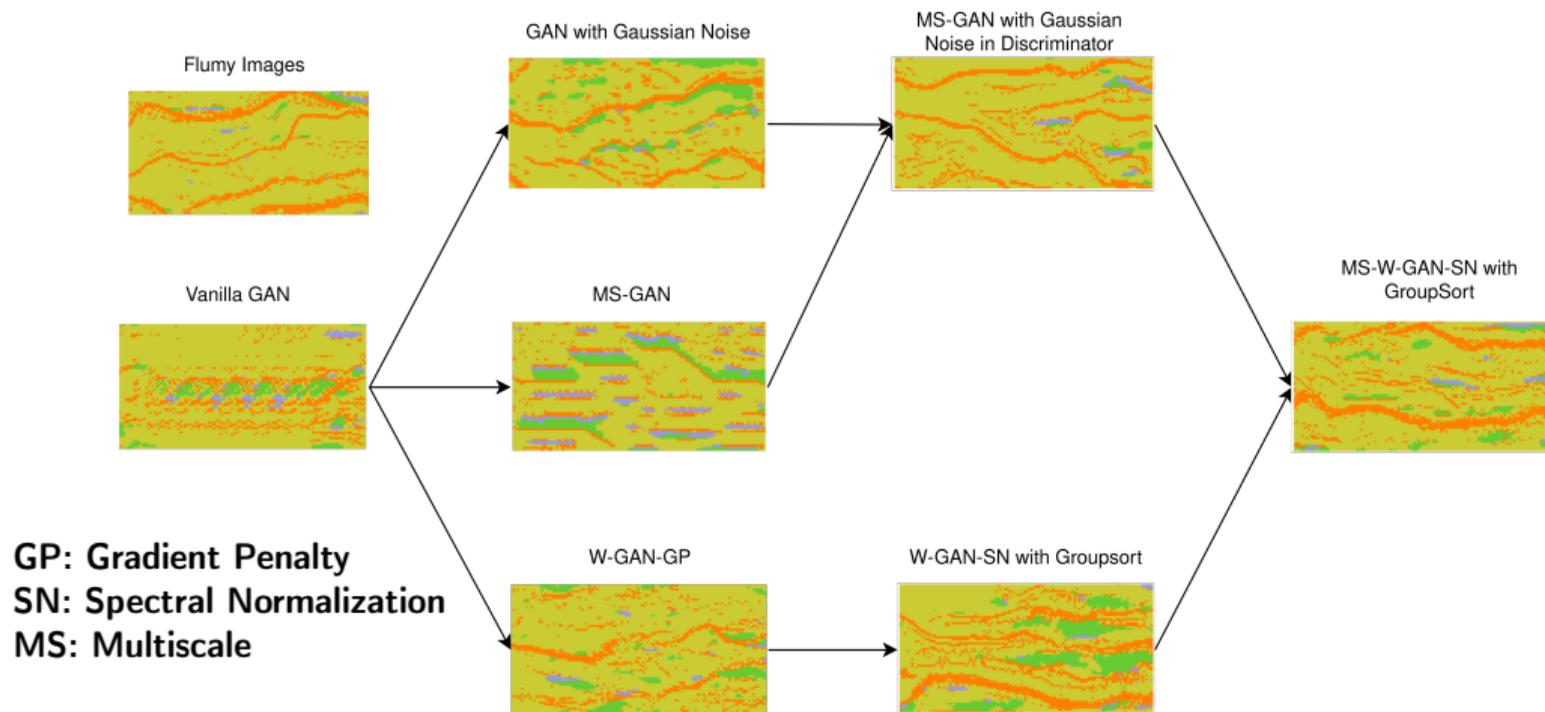


Conditioning the GAN model: Results

We also compare the percentage of successfully predicted observation pixels:



Stabilization techniques journey



GANs models for spatial simulation:

Pros

- **Good results**, both in 2D and 3D
- **Quick** simulation once trained
- Can be **conditioned** using Bayesian scheme

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Pros

- **Good results**, both in 2D and 3D
- **Quick** simulation once trained
- Can be **conditioned** using Bayesian scheme

Cons

- Hard to train, **unstable**, need a lot of stabilization

① Generative Adversarial Networks (GANs)

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Conditioning GANs

② Discrete denoising diffusion models (DDM)

Categorical denoising diffusion

Conditioning DDMs

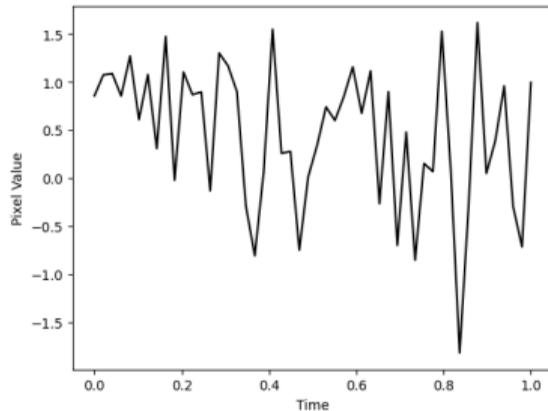
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Problem

Our data is not continuous, but discrete (facies types).
But the framework is ill adapted for discrete data!

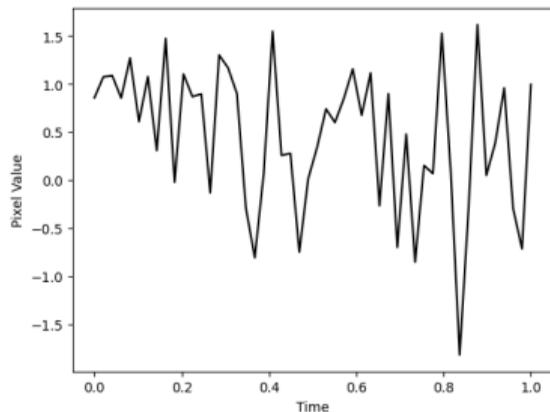


Diffusion noising process for one pixel

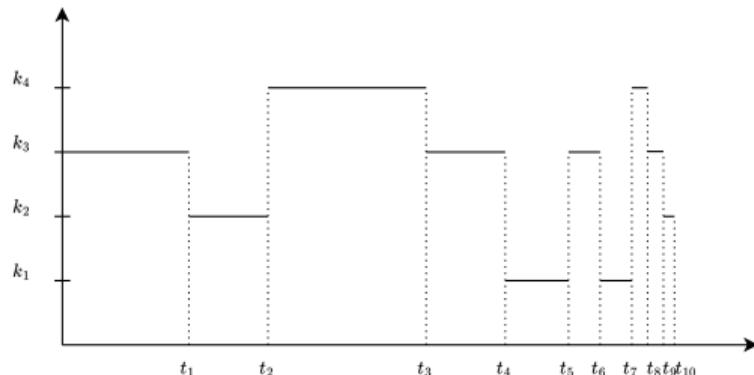
Problem

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But the framework is ill adapted for discrete data! We use **Markov Jump Process**!

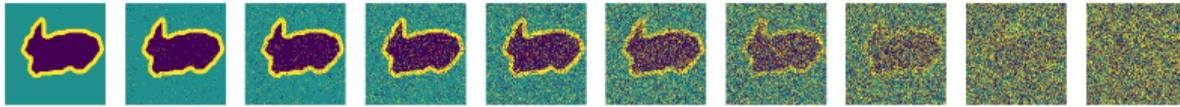


Diffusion noising process for one pixel



Noising Markov jump process for one pixel

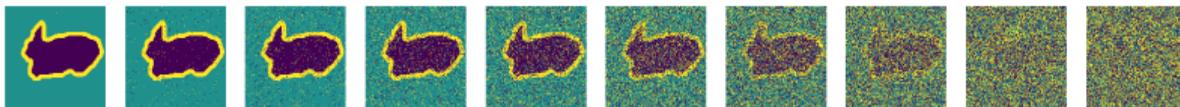
Denosing diffusion models on categorical data



Application of the forward Markov Jump Process (Noising)

Continuous Markov Jump Process $X(t)$, finite state space K .

Denosing diffusion models on categorical data



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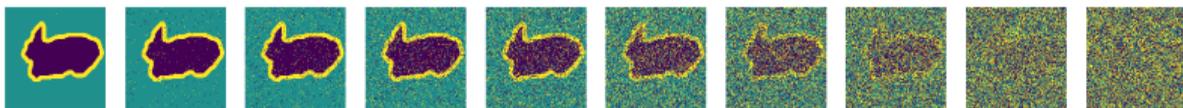
Continuous Markov Jump Process $X(t)$, finite state space K .

Probability at any time t :

$$p(x_t | X_0 = x_0) = e^{\int_0^t Q(s) ds} x_0$$

where $Q(t)$ is the generator matrix of the process.

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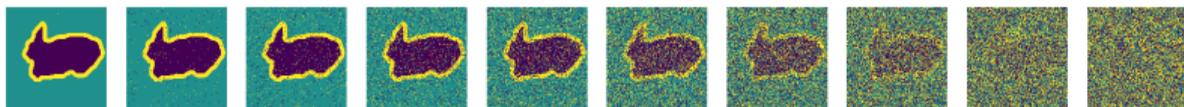
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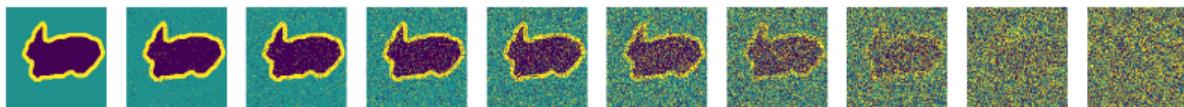
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$$D_\theta(x_t, t) = \hat{x}_0$$

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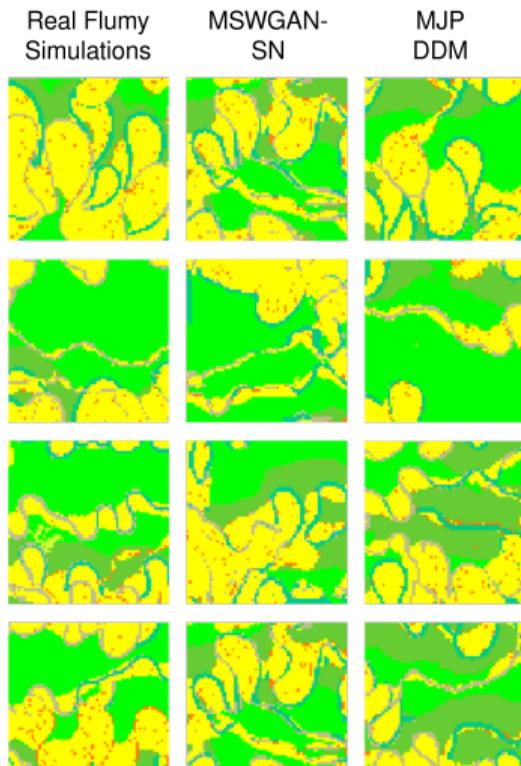
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Trained to give an approximation of x_0 given t and x_t :

$$\theta^* = \underset{\theta}{\operatorname{argmin}} D_{KL} \left(p(x_{t-h} | x_t, x_0) \parallel p_\theta(x_{t-h} | x_t) \right)$$

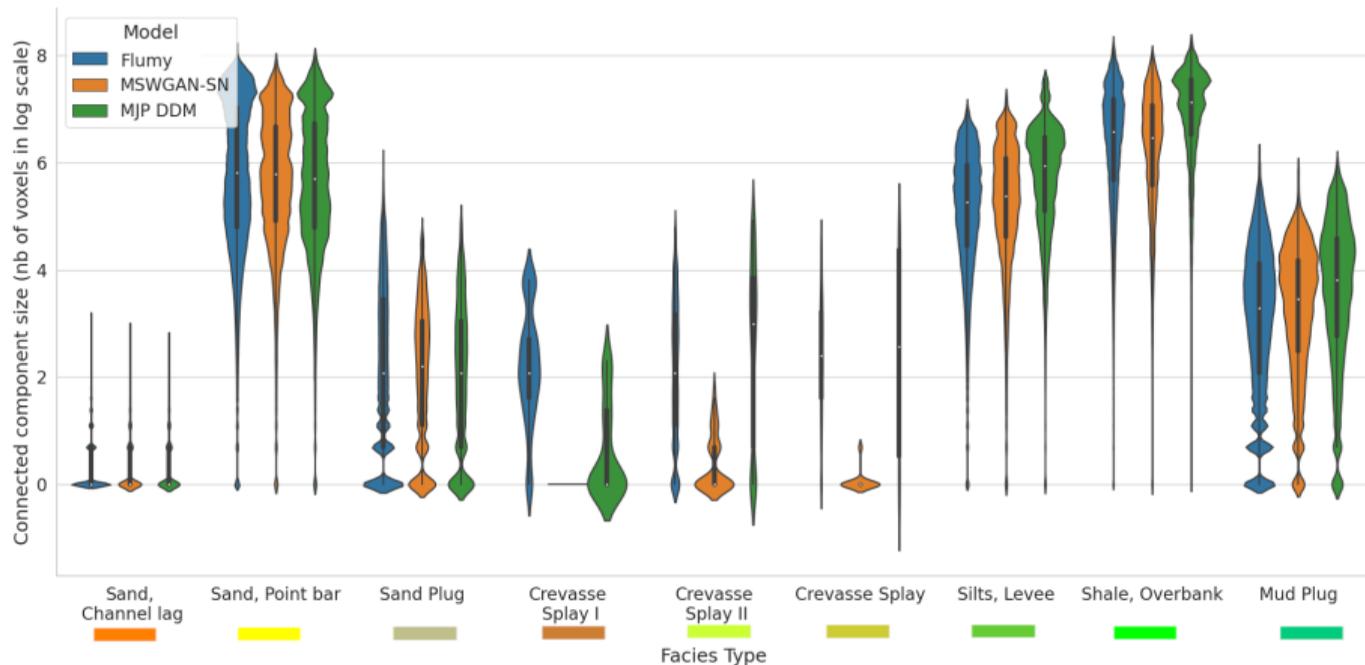
Diffusion & GANs: 9 facies dataset



- New Flumy dataset
- In-depth comparison GANs & Diffusion

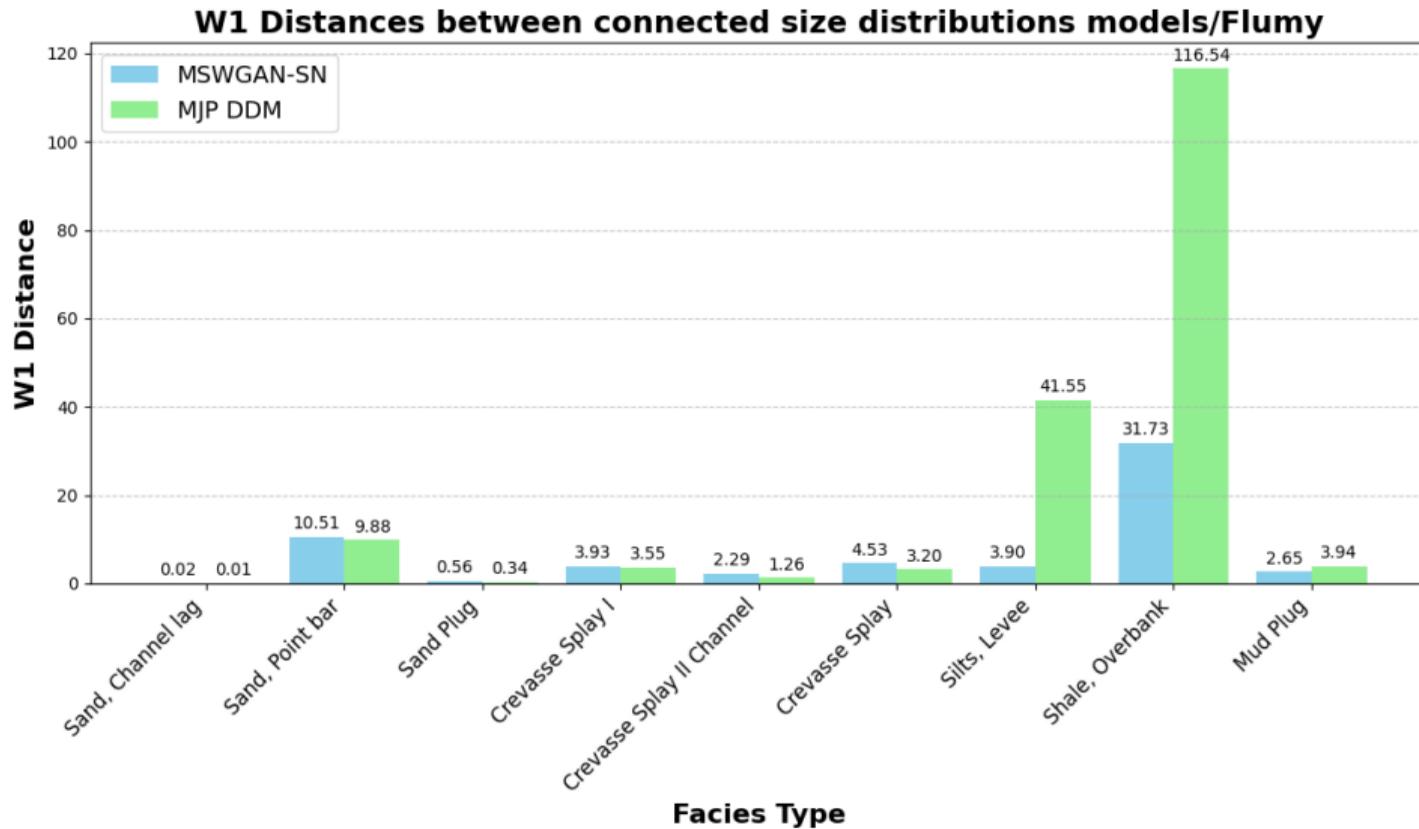


9 facies: connected components

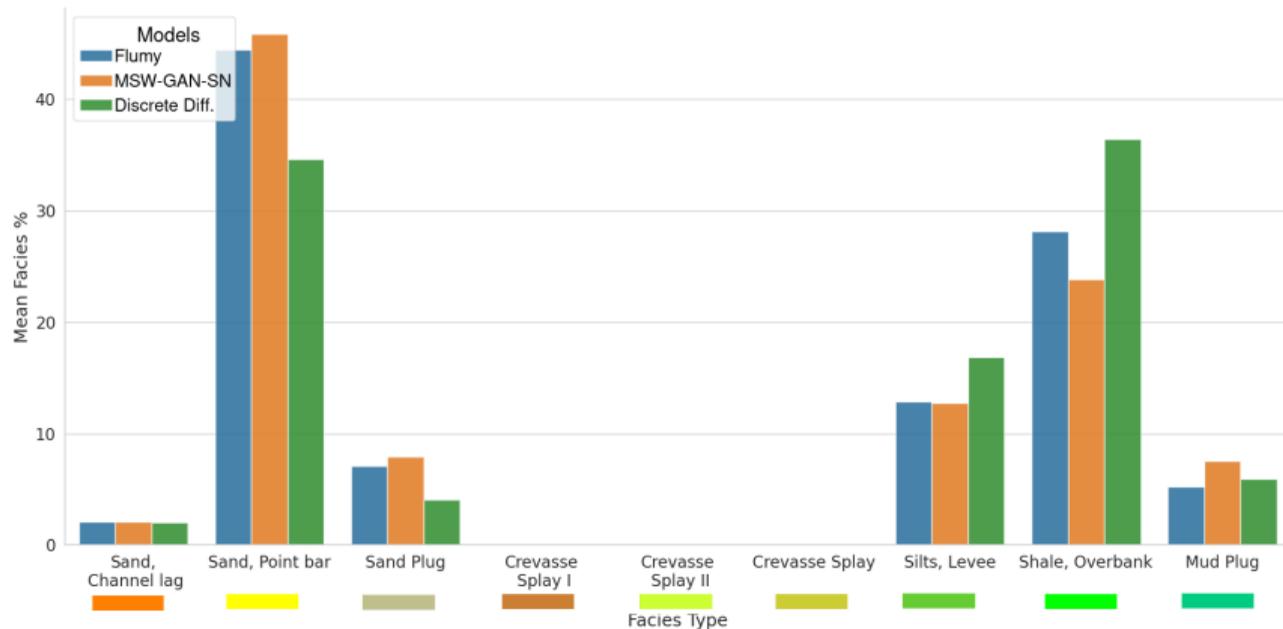


Size of connected of different facies for our GAN and DDM model, in the 9 facies scenario.

9 facies: connected components

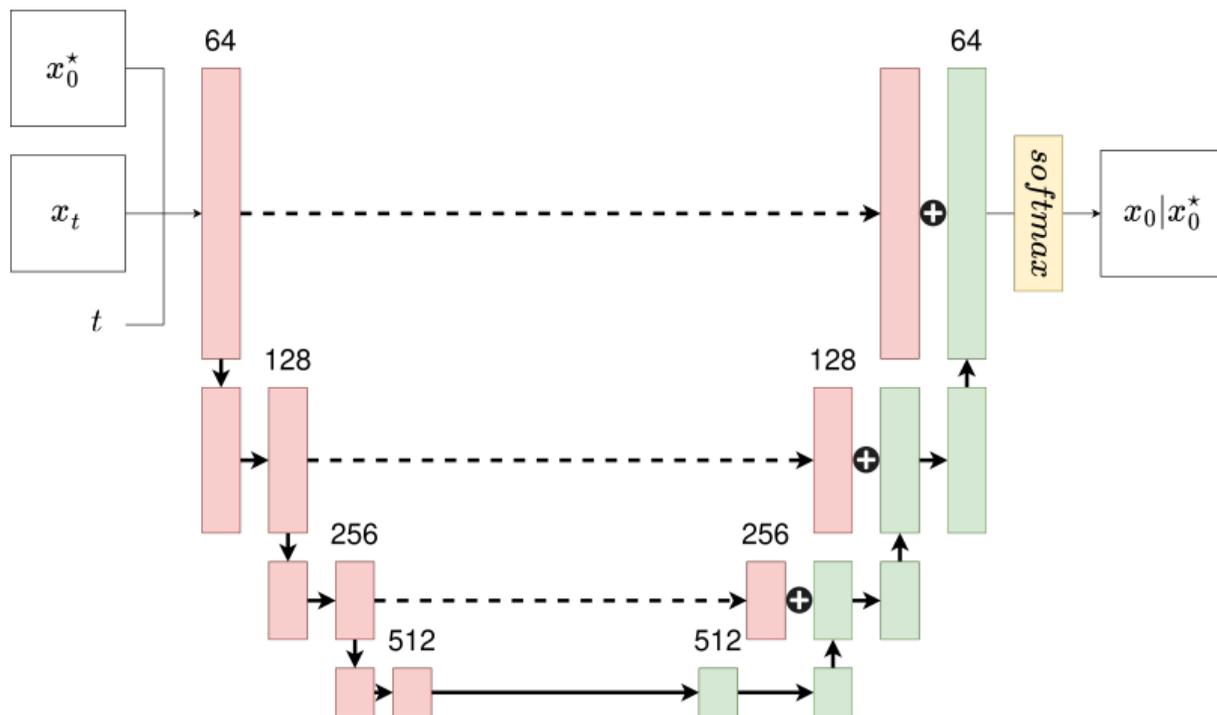


9 facies: proportions of facies



Proportion of different facies for our GAN and DDM model, in the 9 facies scenario.

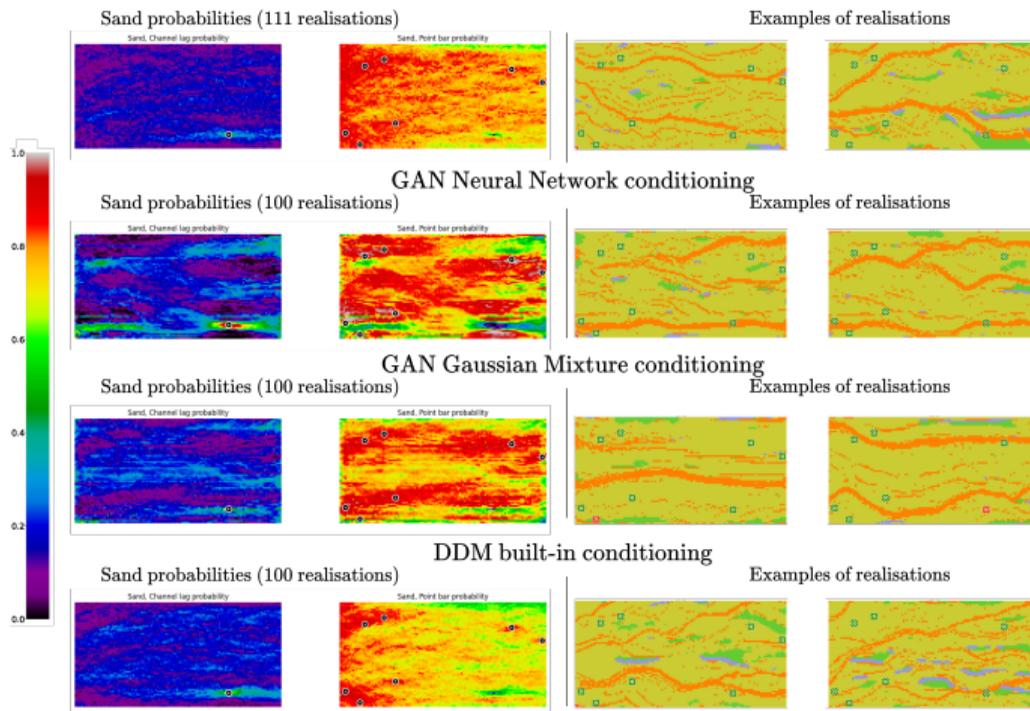
Conditioning DDMs



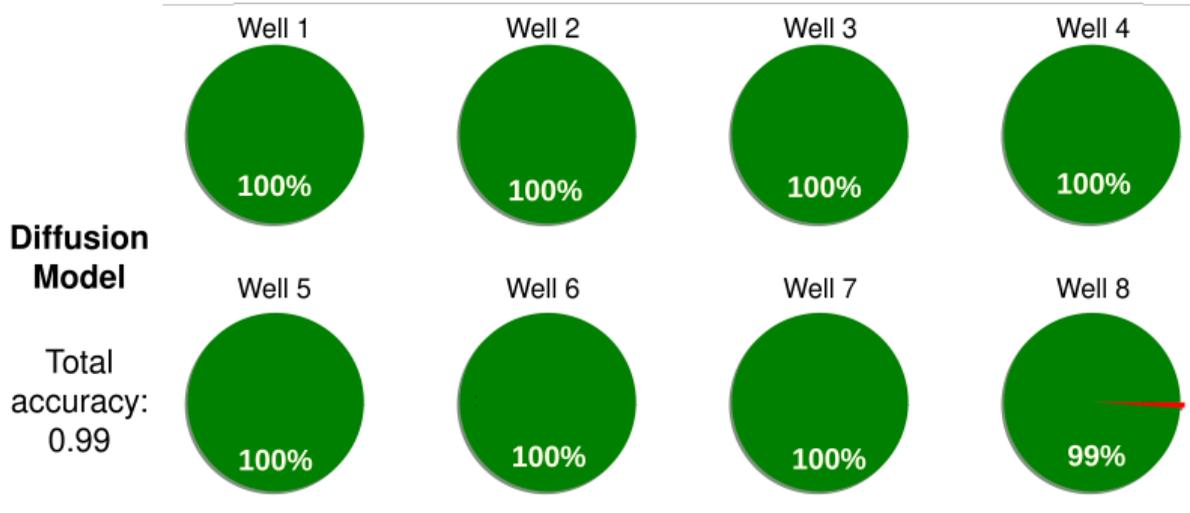
Built-in conditional architecture for DDM, with 4 separate inputs.

$$p(x_0|x_t, x_0^*)$$

Generator simulations accept-reject



Percentage of correctly predicted observation per well



Comparison of the percentage of success for DDM conditioning methods.

Our "Diffusion" model is an alternative to our previous GAN model even for discrete data generation.

Pros

- More **stable** than GANs
- DDMs **minimize a well-defined objective function**
- Conditioning method gives better results

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- Conditioning method gives better results

Cons

- **Slow inference** compared to GANs (step by step)
- Our model is not as good as GANs on our metrics (proportion problems)

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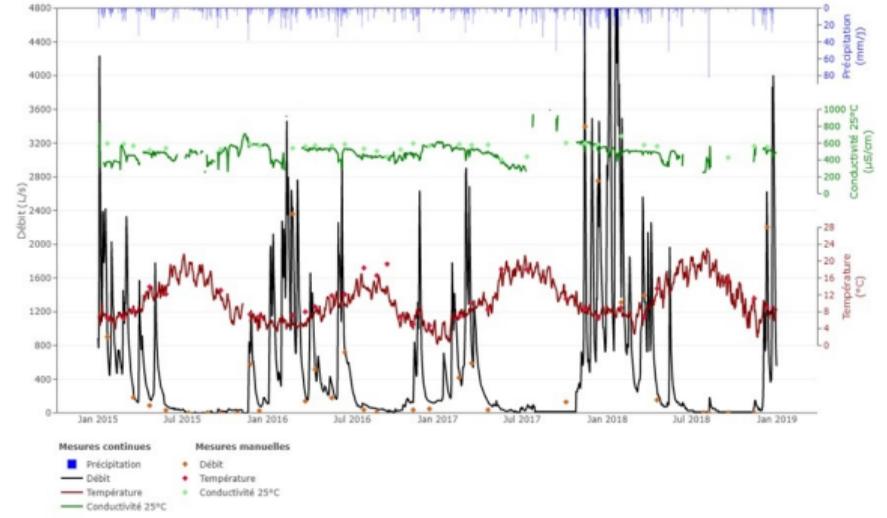
ANDRA data around the CIGEO nuclear waste disposal site.

- ① Water level
- ② Temperature
- ③ pH
- ④ Conductivity at 25°C
- ⑤ Dissolved O₂
- ⑥ O₂ saturation
- ⑦ Nitrates concentration
- ⑧ Turbidites
- ⑨ FDom (Fluorescent Dissolved Organic Matter) / Organical Carbon
- ⑩ PAH (Polycyclic Aromatic Hydrocarbon)



Source: Andra

ANDRA data around the CIGEO nuclear waste disposal site. Range: 2012-2024
Step: Every 4 hours



Very sparse field samples and observations around the site. Even cleaned we still have 500 or so
Which to keep ?

```
Index(['OPE90011 - 2,4-D', 'OPE90011 - 2,4-MCPA', 'OPE90011 - AMPA',  
      'OPE90011 - Acenaphtene', 'OPE90011 - Acenaphtylene',  
      'OPE90011 - Acide monochloroacetique', 'OPE90011 - Aclonifene',  
      'OPE90011 - Alachlore', 'OPE90011 - Aldrine', 'OPE90011 - Aluminium',  
      ...  
      'OPE90014 - Thiabendazole', 'OPE90014 - Titre Alcalimetricque Complet',  
      'OPE90014 - Tributyletain-cation', 'OPE90014 - Trichloroethylene',  
      'OPE90014 - Triclosan', 'OPE90014 - Trifluraline',  
      'OPE90014 - Turbidite', 'OPE90014 - Xylene-ortho', 'OPE90014 - Zinc',  
      'OPE90014 - pH'],  
      dtype='object', length=521)
```

Forecasting:

- 1 N-BEATS (Oreshkin et al. 2019) [univariate time-series]
- 2 TimesNet (Wu et al. 2023) [multivariate time-series]

Simulation:

- 1 Time-Series GANs (Yoon et al., 2019)
- 2 TTS-GAN (Li et al., 2022)
- 3 FinGAN (Vuletić et al., 2024)
- 4 Retrieval-Augmented Diffusion Models (Liu et al., 2024)
- 5 ...

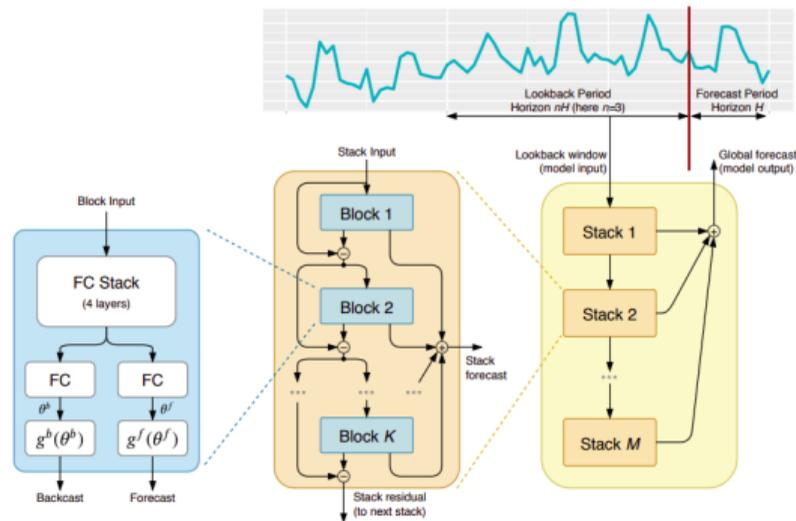
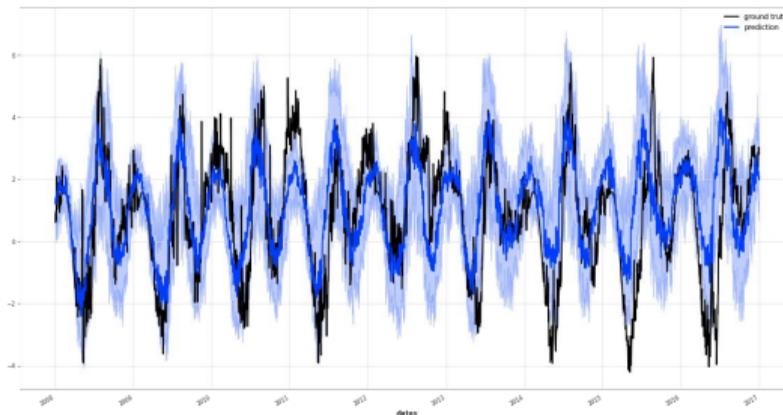


Image source: Neural Basis Expansion Analysis for interpretable Time-series forecasting (NBEATS), Oreshkin et al., 2020

Plan:

- 1 Simulate 1 station [GAN ? Diffusion ?]
- 2 Take into account field observations/samples [Parametrization]
- 3 Simulate all stations
- 4 Time-series inputation (spatial or temporal) [Conditioning]
- 5 Simulate all area [???



Potential of deep generative models (GANs and DDMs) for spatial simulations:

- Flexible & realistic, as was our objective
- Allows to easily generate thousands of simulations for uncertainty estimation

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Postdoctoral research:

- Fix the bias in the denoising model
- Generate temporal and spatio-temporal data

- Bhavsar, F., N. Desassis, F. Ors, and T. Romary (2024). A stable deep adversarial learning approach for geological facies generation. *Computers & Geosciences* 190, 105638.
- Campbell, A., J. Benton, V. D. Bortoli, T. Rainforth, G. Deligiannidis, and A. Doucet (2022). A continuous time framework for discrete denoising models.
- Chan, S. and A. H. Elsheikh (2019, jul). Parametric generation of conditional geological realizations using generative neural networks. *Computational Geosciences* 23(5), 925–952.
- Flumy-Userguide (2022). FLUMY: Process-based channelized reservoir models. Free download from: <https://flumy.minesparis.psl.eu>.
- Lopez, S. (2003, 06). Channelized reservoir modeling: a stochastic process-based approach.